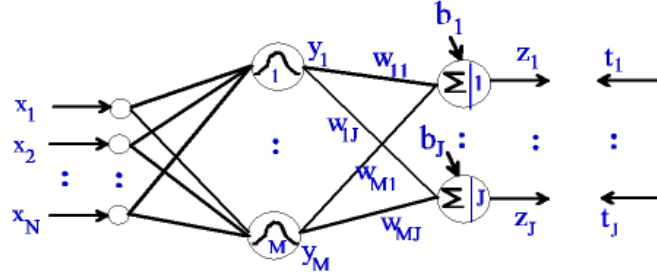


Derivation of the Steepest Descent Algorithm for Radial Basis Function Neural Networks



$$y_m^{(q)} = \exp[-\|x^{(q)} - c^{(m)}\|^2 / (2\sigma_m^2)] \quad (1)$$

$$E = \sum_{q=1}^Q \sum_{j=1}^J (z_j^{(q)} - t_j^{(q)})^2 \quad (2)$$

$$z_j = \sum_{m=1}^M w_{mj} y_m + b_j \quad (3)$$

The method of *steepest descent* from differential calculus is used for the derivation. To solve respectively for the weights $\{w_{mj}\}$, we use the standard formulation

$$w_{mj} \leftarrow w_{mj} - \eta [\partial E / \partial w_{mj}]$$

where the factor η is the step size, or *learning rate*.

Upon using the equations below the diagram above, we derive the partial derivative. To keep the values small for less error build-up, we divide E by the factor QJ.

We take the partial derivative of E as given in Equation (2) above, except that we divided E by QJ to keep the values small.

$$\partial E / \partial w_{mj} = [\partial E / \partial z_j] [\partial z_j^{(q)} / \partial w_{mj}] = [\partial / \partial z_j] (1/QJ) \sum_{(q=1, Q)} (z_j^{(q)} - t_j^{(q)})^2 [\partial z_j^{(q)} / \partial w_{mj}] =$$

$$(2/QJ) \sum_{(q=1, Q)} (z_j^{(q)} - t_j^{(q)}) [\partial z_j^{(q)} / \partial w_{mj}] = (2/QJ) \sum_{(q=1, Q)} (z_j^{(q)} - t_j^{(q)}) [y_m]$$

Thus the steepest algorithm becomes

$$w_{mj} \leftarrow w_{mj} - \eta (2/QJ) \sum_{(q=1, Q)} (z_j^{(q)} - t_j^{(q)}) [y_m]$$